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## BLOW UP VERSUS GLOBAL BOUNDEDNESS OF SOLUTIONS OF REACTION DIFFUSION EQUATIONS WITH NONLINEAR BOUNDARY CONDITIONS\*

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**Abstract.** In this paper we analyze the behavior of solutions of reaction-diffusion equations with nonlinear boundary conditions of the type (1.1). We show that if  $f(x, u) = -\beta_0 u^p$  and  $g(x, u) = u^q$  in a neighborhood of a point  $x_0 \in \Gamma_N$ , then

- i) for the case  $q > 1$ , if  $p + 1 < 2q$  or if  $p + 1 = 2q$  and  $\beta_0 < q$ , then blow up in finite time at  $x_0$  occurs.
- ii) for the case  $p > 1$  if  $p + 1 > 2q$  or if  $p + 1 = 2q$  and  $\beta_0 > q$  then any solution is globally bounded around the point  $x_0$ .

**Key words.** reaction-diffusion, nonlinear boundary conditions, blow-up, boundedness

**1. Introduction.** We consider the following reaction diffusion equation with nonlinear boundary conditions in a smooth  $C^2$  domain  $\Omega \subset \mathbb{R}^N$ ,

$$\begin{cases} u_t - \Delta u = f(x, u) & \text{in } \Omega \\ u = 0 & \text{on } \Gamma_D \\ \frac{\partial u}{\partial \vec{n}} = g(x, u) & \text{on } \Gamma_N \\ u(0, x) = u_0(x) \geq 0 & \text{in } \Omega \end{cases} \quad (1.1)$$

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where  $\Gamma = \partial\Omega = \Gamma_D \cup \Gamma_N$  is a regular disjoint partition of the boundary of  $\Omega$  and  $f$  and  $g$  are suitably smooth functions of  $(x, u)$ . The subindices  $D$  and  $N$  on  $\Gamma$  indicate the part of the boundary with Dirichlet and Neumann type condition, respectively. We are interested in nonnegative solutions of (1.1) so we will assume

$$f(x, 0) \geq 0, \text{ for all } x \in \Omega, \quad g(x, 0) \geq 0 \text{ for all } x \in \Gamma_N$$

We want to obtain local conditions on the nonlinearities  $f$  and  $g$ , which will be imposed in a neighborhood of a point  $x_0 \in \Gamma_N$ , that guarantee that either i) there exists initial conditions with support in a neighborhood of  $x_0$  such that the “proper solution” starting at this initial condition blows up at  $x_0$  or that ii) for all initial data  $u_0 \in L^\infty(\Omega)$  the “proper solution” starting at  $u_0$  is bounded in a neighborhood of  $x_0$  for all times  $t \geq 0$ . We refer to [4, 8, 9] for the concept of proper solution.

Notice that if  $f(x, u)$  behaves like  $u^p$  locally around certain point  $z \in \Omega$  and  $p > 1$ , then, by comparison with the Dirichlet problem in a neighborhood of  $z$  and using that the superlinear nonlinearity  $u^p$  is explosive we get that, regardless of the behavior of  $g$ , we have initial conditions that blow-up in finite time. On the other hand, if  $f(x, u)$  behaves like  $-u^p$  and  $g(x, u)$  behaves like  $-u^q$  throughout the whole domain, then both nonlinearities are dissipative and we have global existence and boundedness of solutions. The most interesting case is when  $f(x, u)$  is a dissipative nonlinearity of the form  $-\beta_0 u^p$  and  $g(x, u)$  is an explosive nonlinearity of the form  $u^q$ . This two mechanisms are in competition and it seems clear that the relative size of  $p$ ,  $q$  and  $\beta_0$  will determine the relative strength of both mechanisms.

Actually, in the pioneer work of [6] they treated the one dimensional case, say  $\Omega = (0, 1)$ , with  $f(x, u) = -\beta_0 u^p$ ,  $g(x, u) = u^q$  and  $\Gamma_D = \emptyset$  and they already obtained that the critical relations are  $p + 1$  vs.  $2q$  and if  $p + 1 = 2q$  then  $\beta_0$  vs.  $q$ , in the sense that if  $p + 1 < 2q$  or  $p + 1 = 2q$  and  $\beta_0 < q$  then blow-up is produced and if  $p + 1 > 2q$  or  $p + 1 = 2q$  and  $\beta_0 > q$  then the solutions are globally bounded. They also treated the very delicate case where  $p + 1 = 2q$  and  $\beta_0 = q$ . They actually showed that the solutions were defined for all time  $t > 0$  but the phenomenon of infinite time blow-up was present.

Later on, in [13, 14], they treated the case of arbitrary dimension and obtained that if



$\Gamma_D = \emptyset$  and the nonlinearities  $f$  and  $g$  that behave for  $u$  large as  $f \sim -\beta_0 u^p$  and  $g \sim u^q$ , then blow-up is produced if  $p+1 < 2q$  or if  $p+1 = 2q$  and  $\beta_0 < q$ . Also, they showed that if  $p+1 > 2q$  or if  $p+1 = 2q$  and  $\beta_0$  is large enough, then the solutions are globally bounded. Also, in [1] they studied the porous medium equation in any dimension and as a particular case they considered the equation (1.1) with  $\Gamma_D = \emptyset$ ,  $f(x, u) = -\beta_0 u^p$  and  $g(x, u) = u^q$ . They showed that if  $p+1 < 2q$  or  $p+1 = 2q$  and  $\beta_0 < q$  then blow-up is produced and if  $p+1 > 2q$  or  $p+1 = 2q$  and  $\beta_0 > q$  then the solutions are globally bounded.

With all these works it is clear that the critical relations that mark the line between blow-up and boundedness are given by  $p+1$  vs.  $2q$  and in case  $p+1 = 2q$ ,  $\beta_0$  vs.  $q$ . These works have a common characteristic and it is that the nonlinear boundary condition is imposed in the whole domain,  $\Gamma_D = \emptyset$  and the construction of sub or super solutions is done for the whole domain. Hence, the balances between  $f$  and  $g$  need to hold throughout the domain to obtain the result and both, the blow-up and the boundedness result are global in space. In particular, none of them can treat the case as in the equation (4.1) where  $p+1 = 2q$  but in some part of the boundary the relation is  $\beta_0 > q$  and in other part the relation is  $\beta_0 < q$  or even when  $\Gamma_D \neq \emptyset$ .

In this paper we will prove that both mechanisms (dissipativeness vs. blow-up) compete at a local level. Actually, we will show that if  $f(x, u) = -\beta_0 u^p$  and  $g(x, u) = u^q$  in a neighborhood of a point  $x_0 \in \Gamma_N$ , then

- i) for the case  $q > 1$ , if  $p+1 < 2q$  or if  $p+1 = 2q$  and  $\beta_0 < q$ , then blow up in finite time at  $x_0$  occurs, see Section 2.
- ii) for the case  $p > 1$  if  $p+1 > 2q$  or if  $p+1 = 2q$  and  $\beta_0 > q$  then any solution is globally bounded around the point  $x_0$ , see Section 3.

In Section 2 we analyze the first case and we refer to [3] for details. In Section 3 we consider the case ii) and we announce the results of [2]. In Section 4 we consider several important remarks and comments.

**2. Localization of blow-up.** In terms of characterizing the sizes of  $p$ ,  $q$  and  $\beta_0$  that will produce blow-up we have:

**PROPOSITION 2.1.** *Let  $x_0 \in \Gamma_N$ ,  $p \geq 1$ ,  $q > 1$  and let  $R_0 > 0$ ,  $M_0 > 0$  such that*

$$\begin{aligned} f(x, u) &\geq -\beta_0 u^p, & x \in B(x_0, R_0) \cap \Omega, & u \geq M_0, \\ g(x, u) &\geq u^q, & x \in B(x_0, R_0) \cap \partial\Omega, & u \geq M_0. \end{aligned} \quad (2.1)$$

*If one of the two following conditions holds*

- i)  $p + 1 < 2q$  or*
- ii)  $p + 1 = 2q$  and  $\beta_0 < q$ ,*

*then, there exists an initial condition  $0 \leq u_0 \in L^\infty(\Omega)$  with support in a neighborhood of  $x_0$  such that the proper minimal solution of (1.1) starting at  $u_0$  blows up in finite time at the point  $x_0$ .*

*Proof.* Let us provide a proof of ii). Actually this case is more critical than i).

In order to simplify, consider that  $x_0 = 0 \in \Gamma_N$  and that the outward normal vector at  $x_0 = 0$  is given by  $\vec{n}(0) = (0, \dots, 0, -1)$ . Let  $R, \delta > 0$  be small numbers and  $y_R = x_0 + R\vec{n}(x_0) = (0, \dots, 0, -R)$  with the property that  $B(y_R, R) \cap \bar{\Omega} = \emptyset$  and that  $B(y_R, R + \delta) \subset B(0, R_0/2)$ . The fact that the domain has a  $C^2$  boundary, guarantees that this construction can be done. See FIG. 2.1.

We will construct a function  $z(t, x)$  which will be radially symmetric around  $y_R$ , increasing in time and that it will be a subsolution of (1.1) locally around the point  $x_0$ . For this, define for  $a \geq 1$ , the function  $\psi_a(t)$  as the solution of the problem

$$\begin{cases} \psi' = \psi^q, \\ \psi(0) = a. \end{cases} \quad (2.2)$$

Solving this equation, we get that  $\psi_a(t) = \frac{E}{(T_a - t)^{\frac{1}{q-1}}}$  for  $-\infty < t < T_a$  with  $E = \frac{1}{(q-1)^{\frac{1}{q-1}}}$  and  $T_a = \frac{1}{(q-1)a^{q-1}}$ . Observe that, since  $a \geq 1$  and  $q > 1$ ,  $T_a \leq 1/(q-1)$  and that  $T_a \rightarrow 0$  as  $a \rightarrow +\infty$ . Notice also that  $\psi_a(t) \leq E/(-t)^{1/(q-1)}$  for any  $t < 0$  and any  $a \geq 1$ .

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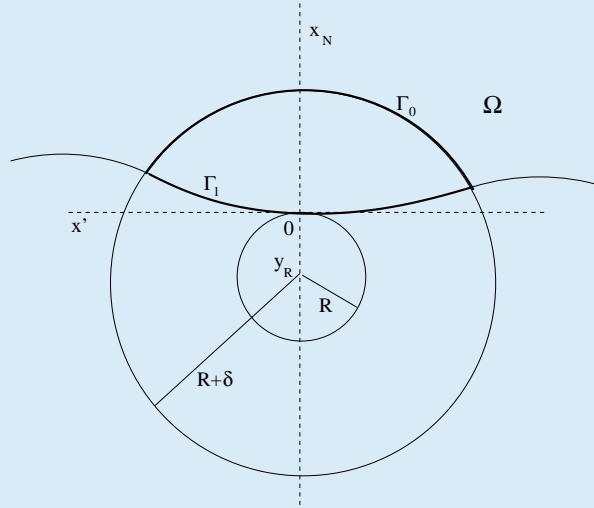


FIG. 2.1. The domain  $\Omega$  near  $x_0$ .

We define  $z_a(t, x) = \psi_a(t + R - |x - y_R|)$  for  $x \in \mathbb{R}^N \setminus B(y_R, R)$ ,  $0 \leq t < T_a$ , see FIG. 2.3.

Direct computations show that  $\frac{\partial z_a}{\partial t} \leq z_a^q$  for  $x \in \Gamma_1$  and  $0 < t < T_a$  and  $\frac{\partial z_a}{\partial t} - \Delta z_a \leq (1 + \frac{N-1}{R} - qz_a^{q-1})z_a^q$  for  $x \in \Omega \cap B(y_R, R + \delta)$  and  $t \in (0, T_a)$ . Notice that  $z_a$  is increasing in time and that  $z_a(t, x) \geq z_a(0, x) = \psi_a(R - |x - y_R|) = \psi_a(-\delta) = \frac{E}{(T_a + \delta)^{\frac{1}{q-1}}} \rightarrow +\infty$  as  $a \rightarrow +\infty$  and  $\delta \rightarrow 0$ , for  $x \in \Omega \cap B(y_R, R + \delta)$ . Hence, choosing  $a_0$  large enough and  $\delta_0$  small enough, we can guarantee, since  $\beta_0 < q$ , that for  $a \geq a_0$  and  $0 < \delta < \delta_0$ , that  $1 + \frac{N-1}{R} - qz_a^{q-1} \leq -\beta_0 z_a^{2q-1} = -\beta_0 z_a^p$  as long as  $x \in \Omega \cap B(y_R, R + \delta)$  and  $0 \leq t < T_a$ .

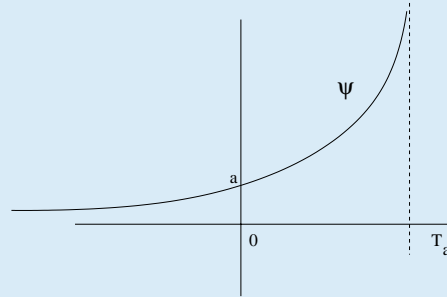


FIG. 2.2. The solution of Equation (2.2).

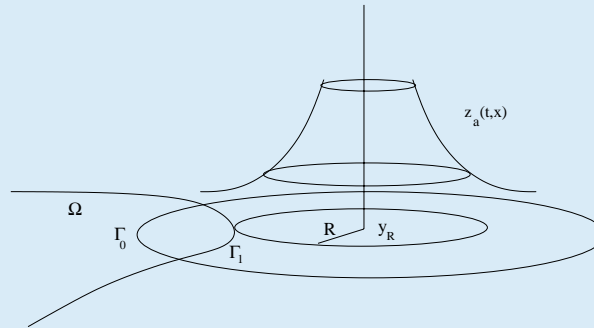


FIG. 2.3. The function  $z_a$ .

In particular, we get

$$\begin{cases} \frac{\partial z_a}{\partial t} - \Delta z_a \leq -\beta_0 z_a^p, & x \in \Omega \cap B(y_R, R + \delta), t \in (0, T_a), \\ \frac{\partial z_a}{\partial n} \leq z_a^q, & x \in \Gamma_1 = \partial\Omega \cap B(y_R, R + \delta), t \in (0, T_a). \end{cases} \quad (2.3)$$

Consider now a smooth initial condition  $v_0 \in C^\infty(\Omega)$  such that  $v_0 \equiv 0$  in  $\Omega \setminus B(0, R_0)$  and  $u_0 \geq \frac{2E}{\delta^{\frac{1}{q-1}}}$  in  $\Omega \cap B(y_R, R+\delta)$ . The solution of (1.1) starting at  $u_0$  will satisfy that for a small time  $T$  we will have that  $u(x, t, v_0) \geq \frac{E}{\delta^{\frac{1}{q-1}}}$  for  $x \in \Gamma_0 \equiv \Omega \cap \partial B(y_R, R+\delta)$ ,  $0 \leq t < T$ . By monotonicity, for any  $u_0 \geq v_0$  in  $\Omega$ , we will also have that the proper solution starting at  $u_0$  will satisfy,  $u(x, t, u_0) \geq \frac{E}{\delta^{\frac{1}{q-1}}}$  for  $x \in \Gamma_0 \equiv \Omega \cap \partial B(y_R, R+\delta)$ ,  $0 \leq t < T$ .

In particular, let us choose  $a > a_0$  with the property that  $0 < T_a < T$  and let us choose  $u_0$  such that  $u_0(x) \geq v_0(x)$  and  $u_0(x) \geq \psi_a(-R) \geq z_a(0, x)$  for  $x \in \Omega \cap B(y_R, R+\delta)$ . Hence, for  $0 \leq t < T_a$  we have  $z_a(t, x) \leq \frac{E}{\delta^{\frac{1}{q-1}}} \leq u(x, t, u_0)$  for  $x \in \Gamma_0$  and  $z_a(0, x) \leq u_0(x)$  for  $x \in \Omega \cap B(y_R, R+\delta)$ . That is,  $z_a$  satisfies,

$$\begin{cases} \frac{\partial z_a}{\partial t} - \Delta z_a \leq -\beta_0 z_a^p, & x \in \Omega \cap B(y_R, R+\delta), t \in (0, T_a), \\ \frac{\partial z_a}{\partial n} \leq z_a^q, & x \in \Gamma_1 = \partial\Omega \cap B(y_R, R+\delta), t \in (0, T_a), \\ z_a(t, x) \leq u(x, t, u_0), & x \in \Gamma_0, t \in (0, T_a), \\ z_a(0, x) \leq u_0, & x \in \Omega \cap B(y_R, R+\delta), \end{cases} \quad (2.4)$$

which implies that  $z_a(t, x) \leq u(t, x, u_0)$  for all  $x \in \Omega \cap B(y_R, R+\delta)$  and  $t \in (0, T_a)$ . The fact that  $z_a(T_a, x)$  blows up at  $x = 0$  proves the result.  $\square$

REMARKS. i) The time  $T_a$  does not need to be the classical blow-up time, that is, the time  $T_\infty$  for which the solution is classical for  $0 < t < T_\infty$  and such that  $\|u(t, \cdot, u_0)\|_{L^\infty(\Omega)} \rightarrow +\infty$  as  $t \nearrow T_\infty$ . We just can assure that  $T_\infty \leq T_a$ .

ii) Observe that if for  $\alpha \in (0, T - T_a)$  we define the function  $w_\alpha(t, x) = z_a(t - \alpha, x)$

defined for  $x \in \Omega \cap B(y_R, R + \delta)$  and  $t \in (\alpha, T_a + \alpha)$ , then, we easily obtain that  $w_\alpha$  satisfies

$$\left\{ \begin{array}{ll} \frac{\partial w_\alpha}{\partial t} - \Delta w_\alpha \leq -\beta_0 w_\alpha^p, & x \in \Omega \cap B(y_R, R + \delta), t \in (\alpha, T_a + \alpha), \\ \frac{\partial w_\alpha}{\partial n} \leq w_\alpha^q, & x \in \Gamma_1 = \partial\Omega \cap B(y_R, R + \delta), t \in (\alpha, \alpha + T_a), \\ w_\alpha(t, x) \leq u(x, t, u_0), & x \in \Gamma_0, t \in (\alpha, \alpha + T_a), \\ w_\alpha(\alpha, x) \leq u_0, & x \in \Omega \cap B(y_R, R + \delta). \end{array} \right. \quad (2.5)$$

The third inequality is obtained since for  $x \in \Gamma_0$  we have  $w_\alpha(t, x) \leq \frac{E}{\delta^{\frac{1}{q-1}}} \leq u(x, t, u_0)$

From (2.5) we obtain that  $w_\alpha(t, x) = z_\alpha(t - \alpha, x) \leq u(t, x, u_0)$  for all  $\alpha \in (0, T - T_a)$ . This implies that for  $t \in (T_a, T)$  we have  $z_\alpha(T_a, x) \leq u(t, x, u_0)$  which means that the solution  $u$  is “pinned” to the value  $\infty$  during the time  $T_a \leq t \leq T$ .

iii) With some extra effort, see [3] for details, it is possible to show that the construction of PROPOSITION 2.1 can be performed in a neighborhood of  $x_0 \in \partial\Omega$ . As a matter of fact the parameters,  $R, \delta, a_0, \delta_0$ , and the initial condition  $u_0$  can be chosen the same for a small neighborhood  $\partial\Omega \cap B(x_0, \eta)$  for  $\eta > 0$  small. This means that the proper solution  $u(t, x, u_0)$  will blow up, not only at  $x_0$  but at  $B(x_0, \eta') \cap \partial\Omega$  for some small  $\eta' > 0$ , and it will remain “pinned” to the value  $\infty$  for a period of time  $T_a \leq t \leq T$ .

**3. Localization of global boundedness.** In this section we present the results of [2] that, roughly speaking, say that if the complementary conditions of PROPOSITION 2.1 hold, also near a point  $x_0 \in \partial\Omega$ , then the proper solution is bounded globally in time around this point  $x_0$ . As a matter of fact, we have

**PROPOSITION 3.1.** *Let  $x_0 \in \Gamma_N, p > 1, q \geq 1$  and let  $R_0 > 0, M_0 > 0$  such that*

$$\begin{aligned} f(x, u) &\leq -\beta_0 u^p, & x \in B(x_0, R_0) \cap \Omega, & u \geq M_0, \\ g(x, u) &\leq u^q, & x \in B(x_0, R_0) \cap \partial\Omega, & u \geq M_0. \end{aligned} \quad (3.1)$$

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If one of the two following conditions holds

- i)  $p + 1 > 2q$  and  $\beta_0 > 0$  or
- ii)  $p + 1 = 2q$  and  $\beta_0 > q$ ,

then, for any initial condition  $0 \leq u_0 \in L^\infty(\Omega)$  the proper solution of (1.1) starting at  $u_0$  is bounded in a neighborhood of  $x_0$  in  $\Omega$ , for all  $t > 0$ . That is, there exist  $\delta, M > 0$  such that

$$\sup_{0 \leq t < \infty, x \in B(x_0, \delta) \cap \Omega} u(t, x, u_0) \leq M. \quad (3.2)$$

To prove the result, we construct appropriate super solutions locally around the point  $x_0 \in \Gamma_N$ . As a matter of fact we extensively use the singular solutions of the following elliptic problem

$$\begin{cases} -\Delta z + \beta z^p = 0 & \text{in } B(0, R), \\ z(R) = +\infty, \end{cases} \quad (3.3)$$

and the fact that the asymptotics of this radial solution as  $r \rightarrow R$  is well understood, see [5, 12].

We refer to [2] for details on the proof of this result.

**4. Concluding Remarks.** We present in this section several important comments and remarks.

- i) Both results are local in nature: if the conditions of PROPOSITION 2.1 (resp. PROPOSITION 3.1) hold in a neighborhood of certain point  $x_0 \in \partial\Omega$ , then, independently of the behavior of the nonlinearities outside this neighborhood, we will have that blow-up (resp. global boundedness of solutions) occurs in the neighborhood of  $x_0$ . In particular, from the control theory point of view it turns out that it is impossible to prevent blow-up (resp. to produce blow-up) in a neighborhood of a point of the boundary of the domain by modifying the equation somehow away from this point.
- ii) With an appropriate rescaling it is not difficult to see that if the local conditions of the nonlinearities  $f$  and  $g$  in PROPOSITION 2.1 and PROPOSITION 3.1 are of the

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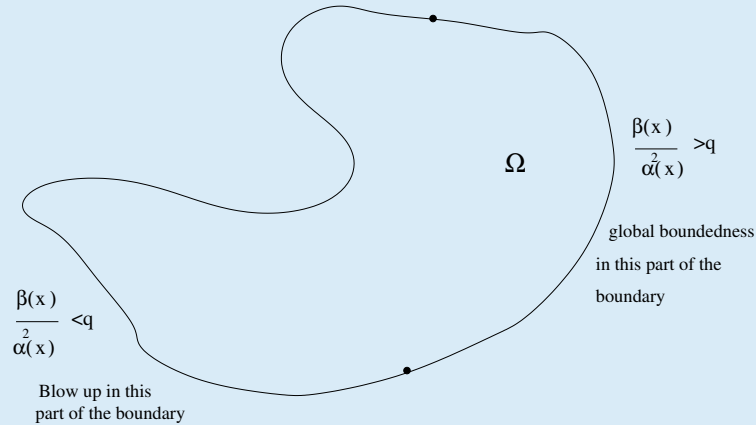


FIG. 4.1. The domain of the example.

type  $f(x, u) \sim -\beta_0 u^p$ ,  $g(x, u) \sim \alpha_0 u^q$ , for  $x \in B(x_0, R_0) \cap \partial\Omega, u \geq M_0$ , then, the condition  $\beta_0 < q$  (resp.  $\beta_0 > q$ ) should be changed to  $\beta_0 > q\alpha_0^2$ , (resp.  $\beta_0 < q\alpha_0^2$ ).

iii) It is important to mention that the balances obtained for  $p$ ,  $q$  and  $\beta_0$  are independent of the dimension of the space and even of the geometry of the domain.

iv) As an example, consider for instance the problem

$$\begin{aligned}
 u_t - \Delta u &= -\beta(x)u^p & \text{in } \Omega, \\
 \frac{\partial u}{\partial \vec{n}} &= \alpha(x)u^q & \text{on } \partial\Omega, \\
 u(0, x) &= u_0(x) \geq 0 & \text{in } \Omega,
 \end{aligned} \tag{4.1}$$

with  $\beta$  and  $\alpha$  continuous functions,  $\beta(x) > 0$  in  $\bar{\Omega}$  and  $\alpha(x) > 0$  in  $\partial\Omega$ , see FIG. 4.1.

Then if  $p + 1 = 2q > 2$  and  $x_0 \in \partial\Omega$  with  $\frac{\beta(x_0)}{\alpha(x_0)^2} < q$  then from [3], there are initial conditions where blow up is produced near  $x_0$ , while if  $\frac{\beta(x_0)}{\alpha(x_0)^2} > q$ , then from THEOREM 2.1 above, for any initial condition  $u_0 \in L^\infty(\Omega)$  the proper minimal solution is bounded near  $x_0$ . Hence, we have the situation as in FIG. 4.1

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